

Table 1

Group Members	Topic/Theme	Status	Comments (if any)			
<b>Ahmed and Ibrahim</b>	Laser Cutting Robot	Approved	It was not clear that how the desired path will be defined. Is it possible to take a user input from a text file maybe? So that user can have different laser cuttings as well.			
<b>Hilary</b>	Bottling and Packaging	Approved	It is not clear how the bottle filling is performed and how it will be determined?			
<b>Emir and Berat</b>	Sorting and Palletizing	Not approved	About the detection of different boxes, it is not clear whether you are referring to different colours or different sizes.			
<b>Efe and Efe :)</b>	Sorting and Palletising	Not approved	Similar to Emir and Berat, talk to them, one of you should change your project			
<b>Eren</b>	Spraying	Not approved	We also attempted the same task during our lecture, moreover it is a relatively simple task. Can you think of one robot or multiple robots that are able to spray car from inside or you can also think of art painting robot or a robot that can paint some furniture such as chair?			
<b>Mahmoud and Salman</b>	Paint Spraying	Approved	What does the controller show in your figure?			
<b>Mehmet and Alperen</b>	Color based sorting and drilling	Approved	It is not clear whether the holes are made at specific places in the parts? How many sensors will be utilised?			
<b>Muhammed Ali</b>	Soldering robot	Approved	how are you going to provide the PCB layout for soldering? The term autonomous is a bit confusing here, all you want is a PCB layout and soldering will be done. The usage of camera is also not clear, because the soldering station is fixed, slots are also fixed, size between slots are also fixed.			

